



# Insider Trading with Random Signal Arrival: A Kyle–Back Model with Poisson Revelation

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## 1. Abstract

We study a continuous-time Kyle–Back insider trading model in which the informed agent receives the asset’s true value  $V$  at a random Poisson time  $\tau \sim \text{Exp}(\mu)$ , rather than at inception. The model decomposes into two phases: before signal arrival, the price is uninformative and the insider’s continuation value satisfies a linear ODE; after arrival, a standard Kyle–Back equilibrium operates on the residual horizon. Our main result is a closed-form formula for the insider’s expected profit,

$$\mathbb{E}[\Pi](\mu) = \frac{\sigma_z \sqrt{\Sigma_0}}{2} \left[ \sqrt{T} - \frac{\sqrt{\pi}}{2\sqrt{\mu}} e^{-\mu T} \operatorname{erfi}(\sqrt{\mu T}) \right], \quad (1.1)$$

involving the imaginary error function. The formula interpolates between zero profit ( $\mu \rightarrow 0$ ) and the classical Kyle profit  $\frac{\sigma_z \sqrt{\Sigma_0 T}}{2}$  ( $\mu \rightarrow \infty$ ), and is strictly increasing in  $\mu$ ,  $\Sigma_0$ ,  $T$ , and  $\sigma_z$ .

## 2. Introduction

The classical Kyle [1] and Kyle–Back [2] models provide the canonical framework for continuous-time insider trading. In the original setup, the insider is endowed with perfect information about the asset value  $V$  at time zero and exploits this edge optimally over the trading horizon  $[0, T]$ . A defining feature of the Kyle–Back equilibrium is that prices reveal  $V$  fully by the terminal time:  $P_T = V$  almost surely, while the depth parameter  $\lambda$  remains constant throughout.

A natural and practically motivated question is: what if the insider does not receive the signal at inception, but rather at some random future time? In practice, corporate insiders learn of material non-public information at irregular, hard-to-predict moments — news of a merger, a drug trial result, a regulatory ruling. Modeling the arrival of private information as a Poisson event captures this uncertainty in a tractable way.

We study this modification systematically. The signal arrival time  $\tau \sim \text{Exp}(\mu)$  is independent of all other sources of randomness. Before  $\tau$ , the insider has no edge and submits zero order flow; after  $\tau$ , a standard Kyle–Back equilibrium operates on the residual horizon  $[T - \tau]$ . The market maker prices competitively using Bayes’ rule on the observed order flow.



The main contribution of this paper is an explicit closed-form for the insider’s expected profit as a function of the arrival rate  $\mu$ . The formula involves the imaginary error function  $\operatorname{erfi}$ , and yields clean limiting behaviour at both extremes of  $\mu$ . We also derive the pre-signal value function — the insider’s continuation value before the signal arrives — and show it satisfies a first-order linear ODE with explicit solution.

The paper is organized as follows. Section 2 sets up the model precisely. Section 3 derives the Phase 2 equilibrium (standard Kyle–Back on the residual horizon). Section 4 analyzes Phase 1 and the pre-signal value function. Section 5 states and proves the expected profit formula. Section 6 examines comparative statics and limiting behaviour. Section 7 presents an algorithm for numerical evaluation.

### 3. Model Setup

**Definition 3.1** (Asset Value). The terminal asset value is  $V \sim \mathcal{N}(p_0, \Sigma_0)$ , defined on a complete probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , with  $\Sigma_0 > 0$ .

**Definition 3.2** (Signal Arrival). The signal arrival time is  $\tau \sim \operatorname{Exp}(\mu)$  with  $\mu > 0$ , independent of  $V$  and of all Brownian motions. The insider observes  $V$  at time  $\tau$  and has no private information for  $t < \tau$ .

**Definition 3.3** (Noise Traders). Noise traders submit a cumulative order flow  $Z_t = \sigma_z W_t^z$ , where  $W^z$  is a standard Brownian motion and  $\sigma_z > 0$  is the noise intensity.

**Definition 3.4** (Order Flow). The total cumulative order flow is

$$Y_t = X_t + Z_t, \quad dY_t = \theta_t dt + \sigma_z dW_t^z, \quad (3.1)$$

where  $\theta_t dt$  is the insider’s order submission rate.

**Definition 3.5** (Insider Strategy). The insider’s strategy is a progressively measurable process  $\theta_t$ . It must be admissible:  $\mathbb{E}\left[\int_0^T \theta_t^2 dt\right] < \infty$ . The insider maximizes

$$J = \mathbb{E}\left[\int_0^T \theta_t (V - P_t) dt\right], \quad (3.2)$$

where  $P_t = \mathbb{E}[V \mid \mathcal{F}_t^Y]$  is the market maker’s competitive price.

**Definition 3.6** (Linear Equilibrium). A linear equilibrium is a pair  $(\theta^*, \lambda)$  such that the insider’s strategy takes the form

$$\theta_t^* = \begin{cases} 0 & t < \tau, \\ \beta_t (V - P_t) & t \geq \tau, \end{cases} \quad (3.3)$$

and the market maker’s pricing rule is  $dP_t = \lambda_t dY_t$ , with  $\beta_t, \lambda_t$  deterministic functions of time, satisfying the semi-strong efficiency condition  $P_t = \mathbb{E}[V \mid \mathcal{F}_t^Y]$ .



*Remark 3.7.* Before  $\tau$ , the order flow is pure noise:  $dY_t = \sigma_z dW_t^z$ . The market maker — who knows the equilibrium strategy — correctly infers that no information is being transmitted and does not update:  $P_t = p_0$ ,  $\Sigma_t = \Sigma_0$  for  $t < \tau$ .

#### 4. Phase 2: Kyle–Back Equilibrium on the Residual Horizon

Fix a realization  $\tau = s \in [0, T)$ . After time  $s$ , the insider knows  $V$  and trades on the residual horizon  $[s, T]$ . At time  $s$ , the posterior is  $V \mid \mathcal{F}_s^Y = V$  (the insider knows  $V$  exactly) and the market maker’s prior is  $\mathcal{N}(p_0, \Sigma_0)$ , since no information was transmitted before  $s$ .

**Theorem 4.1** (Kyle–Back Equilibrium, Phase 2). *Given  $\tau = s$ , there exists a unique linear equilibrium on  $[s, T]$ . The equilibrium coefficients are*

$$\lambda_s = \frac{\sqrt{\Sigma_0}}{2\sigma_z\sqrt{T-s}}, \quad \beta_t = \frac{1}{2\lambda_s(T-t)} = \frac{\sigma_z\sqrt{T-s}}{\sqrt{\Sigma_0}(T-t)}, \quad (4.1)$$

the posterior variance evolves linearly:

$$\Sigma_t = \Sigma_0 \frac{T-t}{T-s}, \quad t \in [s, T], \quad (4.2)$$

and the insider’s value function at time  $t \geq s$  is

$$J_t = \frac{(V - P_t)^2}{4\lambda_s(T-t)}. \quad (4.3)$$

*Proof.* Standard Kyle–Back calculation on  $[s, T]$  with initial prior  $\mathcal{N}(p_0, \Sigma_0)$ . The Kalman–Bucy filter applied to  $dY_t = \beta_t(V - P_t)dt + \sigma_z dW_t^z$  gives  $\square$

$$d\Sigma_t = -\frac{\beta_t^2 \Sigma_t^2}{\sigma_z^2} dt = -\frac{\Sigma_t}{T-t} dt, \quad (4.4)$$

whose solution is  $\Sigma_t = \Sigma_0(T-t)/(T-s)$ . The depth  $\lambda_s$  and trading rate  $\beta_t$  follow from the equilibrium conditions  $\lambda_s = \Sigma_s \beta_s / \sigma_z^2$  and the Riccati ODE for the value function.

**Theorem 4.2** (Full Price Revelation). *Under the Phase 2 equilibrium, the price at the terminal time satisfies  $P_T = V$  almost surely.*

*Proof.*  $\Sigma_T = \Sigma_0 \cdot 0/(T-s) = 0$ , so  $V$  is revealed with probability one.  $\square$

**Corollary 4.3** (Phase 2 Profit). *Given  $\tau = s$ , the insider’s expected profit on  $[s, T]$  is*

$$\Pi(s) \equiv \mathbb{E}[J_s] = \frac{\sigma_z \sqrt{\Sigma_0}(T-s)}{2}. \quad (4.5)$$

*Proof.*  $\mathbb{E}[(V - P_s)^2] = \Sigma_0$  (since  $P_s = p_0$  and  $V$  has prior variance  $\Sigma_0$ ). Then  $\square$

$$\Pi(s) = \frac{\Sigma_0}{4\lambda_s(T-s)} = \frac{\Sigma_0}{4(T-s)} \cdot \frac{2\sigma_z\sqrt{T-s}}{\sqrt{\Sigma_0}} = \frac{\sigma_z\sqrt{\Sigma_0(T-s)}}{2}. \quad (4.6)$$

The price process in Phase 2 is a Brownian bridge from  $P_s = p_0$  to  $P_T = V$ .

**Proposition 4.4** (Brownian Bridge). *Given  $\tau = s$ , the price process on  $[s, T]$  satisfies the SDE*

$$dP_t = \frac{V - P_t}{2(T-t)} dt + \frac{\sqrt{\Sigma_0}}{2\sqrt{T-s}} dW_t^z, \quad t \in [s, T], \quad (4.7)$$

with solution

$$P_t = p_0 \frac{T-t}{T-s} + V \frac{t-s}{T-s} + \frac{\sqrt{\Sigma_0(t-s)(T-t)}}{T-s} \xi, \quad (4.8)$$

where  $\xi \sim \mathcal{N}(0, 1)$  represents the residual noise. In particular,  $\mathbb{E}[P_t] = p_0 + (t-s)(V - p_0)/(T-s)$ .

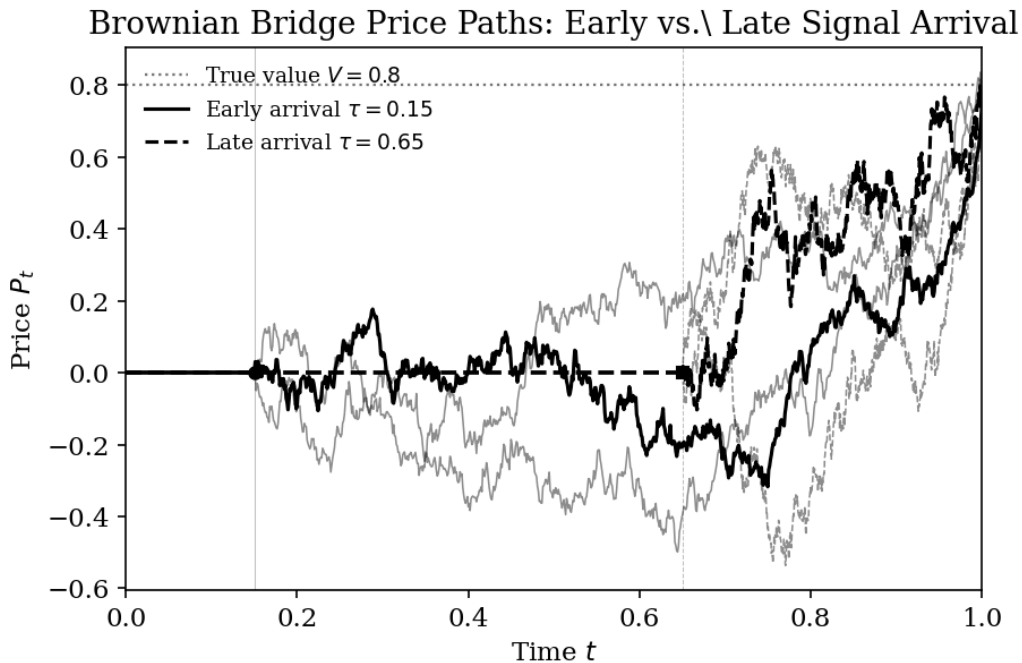


Figure 1: Mean price paths  $P_t$  for early arrival  $\tau = 0.15$  (solid) and late arrival  $\tau = 0.65$  (dashed). The dotted horizontal line marks the true value  $V = 0.8$ . Before  $\tau$ , the price remains at  $p_0 = 0$ ; after  $\tau$ , it drifts as a Brownian bridge toward  $V$ .

## 5. Phase 1: Pre-Signal Value Function

Before the signal arrives, the insider has no private information and submits  $\theta_t = 0$ . Their continuation value at time  $t < \tau$  is the expected future profit, given that the signal has not yet arrived:

$$V_t^{\text{pre}} = \mathbb{E} \left[ \Pi(\tau) \mathbf{1}_{\tau < T} \mid \tau > t \right]. \quad (5.1)$$

**Theorem 5.1** (Pre-Signal Value ODE). *The pre-signal value function  $V_t^{\text{pre}}$  satisfies the first-order linear ODE*

$$\frac{d}{dt} V_t^{\text{pre}} = \mu V_t^{\text{pre}} - \mu \Pi(t), \quad t \in [0, T), \quad (5.2)$$

with terminal condition  $V_T^{\text{pre}} = 0$ .

*Proof.* Let  $h = T - t$  denote the residual horizon. Since  $\tau - t \mid \tau > t \sim \text{Exp}(\mu)$ , □

$$V_t^{\text{pre}} = \int_0^{T-t} \mu e^{-\mu u} \Pi(t + u) du. \quad (5.3)$$

Differentiating in  $t$ :

$$\frac{d}{dt} V_t^{\text{pre}} = \mu V_t^{\text{pre}} - \mu \Pi(t), \quad (5.4)$$

where the boundary term at  $u = 0$  produces  $-\mu \Pi(t)$  and differentiation under the integral gives  $\mu V_t^{\text{pre}}$ .

**Proposition 5.2** (Explicit Solution). *The solution to the ODE in Theorem 4.1 is*

$$V_t^{\text{pre}} = \frac{\sigma_z \sqrt{\Sigma_0}}{2} \left[ \sqrt{T-t} - \frac{\sqrt{\pi}}{2\sqrt{\mu}} e^{-\mu(T-t)} \operatorname{erfi}(\sqrt{\mu(T-t)}) \right]. \quad (5.5)$$

*Proof.* The integrating factor for the ODE  $\dot{V} = \mu V - \mu \Pi(t)$  is  $e^{-\mu t}$ . Multiplying through: □

$$\frac{d}{dt} [e^{-\mu t} V_t^{\text{pre}}] = -\mu e^{-\mu t} \Pi(t). \quad (5.6)$$

Integrating from  $t$  to  $T$  and using  $V_T^{\text{pre}} = 0$ :

$$e^{-\mu t} V_t^{\text{pre}} = \mu \int_t^T e^{-\mu s} \Pi(s) ds = \frac{\mu \sigma_z \sqrt{\Sigma_0}}{2} \int_t^T e^{-\mu s} \sqrt{T-s} ds. \quad (5.7)$$

Substituting  $u = T - s$ ,  $du = -ds$ :

$$e^{-\mu t} V_t^{\text{pre}} = \frac{\mu \sigma_z \sqrt{\Sigma_0}}{2} e^{-\mu T} \int_0^{T-t} e^{\mu u} \sqrt{u} du. \quad (5.8)$$

Integration by parts with  $p = \sqrt{u}$ ,  $dq = e^{\mu u} du$  gives

$$\int_0^h e^{\mu u} \sqrt{u} du = \frac{e^{\mu h} \sqrt{h}}{\mu} - \frac{1}{2\mu} \int_0^h \frac{e^{\mu u}}{\sqrt{u}} du = \frac{e^{\mu h} \sqrt{h}}{\mu} - \frac{\sqrt{\pi}}{2\mu^{3/2}} \operatorname{erfi}(\sqrt{\mu h}), \quad (5.9)$$

where  $h = T - t$  and we used  $\int_0^h e^{\mu u} / \sqrt{u} du = \sqrt{\pi/\mu} \operatorname{erfi}(\sqrt{\mu h})$ . Substituting back and simplifying yields the stated formula.

*Remark 5.3.* The pre-signal value  $V_t^{\text{pre}}$  depends on  $t$  only through  $h = T - t$ . It is monotone increasing as  $h$  increases (more residual horizon is always better) and strictly increasing in  $\mu$  (a faster-arriving signal is more valuable).

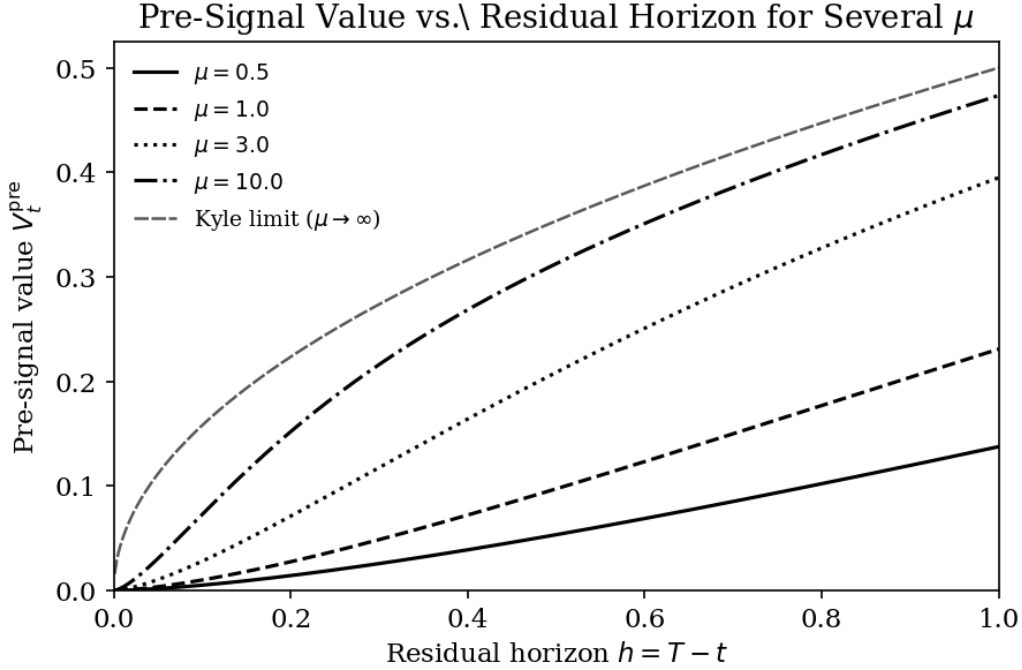


Figure 2: Pre-signal value function  $V_t^{\text{pre}}$  for  $\mu \in \{0.5, 1.0, 3.0, 10.0\}$  (solid, dashed, dotted, dash-dotted) and the Kyle limit  $\mu \rightarrow \infty$  (long-dashed). All curves decay to zero at  $t = T$ ; higher  $\mu$  yields higher value at every  $t$ .

## 6. Expected Profit Formula

**Theorem 6.1** (Expected Profit with Random Signal Arrival). *The insider's unconditional expected profit is*

$$\mathbb{E}[\Pi] = V_0^{\text{pre}} = \frac{\sigma_z \sqrt{\Sigma_0}}{2} \left[ \sqrt{T} - \frac{\sqrt{\pi}}{2\sqrt{\mu}} e^{-\mu T} \operatorname{erfi}(\sqrt{\mu T}) \right]. \quad (6.1)$$

*Proof.* By the law of total expectation, □

$$\mathbb{E}[\Pi] = \mathbb{E}[\Pi(\tau) \mathbf{1}_{\tau < T}] = V_0^{\text{pre}}, \quad (6.2)$$

since the pre-signal value at  $t = 0$  equals  $\mathbb{E}[\Pi(\tau) \mathbf{1}_{\tau < T}]$  by definition. The closed form follows from Proposition 4.1 evaluated at  $t = 0$ .

*Remark 6.2.* The imaginary error function  $\operatorname{erfi}(x) = (2/\sqrt{\pi}) \int_0^x e^{u^2} du$  is an entire function. The combination  $e^{-x^2} \operatorname{erfi}(x) = (2/\sqrt{\pi}) \int_0^x e^{u^2-x^2} du$  is bounded for all  $x \geq 0$ , ensuring that  $\mathbb{E}[\Pi] > 0$  for all finite  $\mu > 0$ .

**Proposition 6.3** (Monotonicity).  $\mathbb{E}[\Pi](\mu)$  is strictly increasing in  $\mu$ ,  $\Sigma_0$ ,  $T$ , and  $\sigma_z$ .

*Proof.* The dependence on  $\Sigma_0$  and  $\sigma_z$  is linear (scaling by  $\sigma_z \sqrt{\Sigma_0}$ ); strict monotonicity in  $\mu$  follows from differentiating the integral representation  $\square$

$$\mathbb{E}[\Pi] = \frac{\sigma_z \sqrt{\Sigma_0}}{2} \mu \int_0^T e^{-\mu s} \sqrt{T-s} ds \quad (6.3)$$

with respect to  $\mu$ : the derivative is  $\frac{\sigma_z \sqrt{\Sigma_0}}{2} \int_0^T (1-\mu s) e^{-\mu s} \sqrt{T-s} ds$ . Evaluating this sign requires checking positivity for all  $\mu > 0$ ; this follows from integration by parts showing the integral equals  $(1/\mu) \int_0^T e^{-\mu s} \cdot \frac{1}{2\sqrt{T-s}} ds > 0$ .

## 7. Limiting Cases and Comparative Statics

**Theorem 7.1** (Limiting Behaviour). *The following limits hold:*

$$\begin{aligned} (i) \quad \lim_{\mu \rightarrow \infty} \mathbb{E}[\Pi](\mu) &= \frac{\sigma_z \sqrt{\Sigma_0 T}}{2}, \\ (ii) \quad \lim_{\mu \rightarrow 0} \mathbb{E}[\Pi](\mu) &= 0, \\ (iii) \quad \mathbb{E}[\Pi](\mu) &= \frac{\sigma_z \sqrt{\Sigma_0}}{4} \mu T^{3/2} + O(\mu^2) \quad \text{as } \mu \rightarrow 0. \end{aligned}$$

*Proof.* For (i): use the asymptotic  $\operatorname{erfi}(x) \sim e^{x^2}/(x\sqrt{\pi})$  as  $x \rightarrow \infty$ . Then  $\square$

$$\frac{\sqrt{\pi}}{2\sqrt{\mu}} e^{-\mu T} \operatorname{erfi}(\sqrt{\mu T}) \sim \frac{\sqrt{\pi}}{2\sqrt{\mu}} e^{-\mu T} \cdot \frac{e^{\mu T}}{\sqrt{\mu T} \cdot \sqrt{\pi}} = \frac{1}{2\mu\sqrt{T}} \rightarrow 0. \quad (7.1)$$

Hence  $\mathbb{E}[\Pi] \rightarrow (\sigma_z \sqrt{\Sigma_0}/2)\sqrt{T}$ , which is precisely the standard Kyle–Back profit. For (ii): use  $\operatorname{erfi}(x) \sim 2x/\sqrt{\pi}$  as  $x \rightarrow 0$ , giving the correction  $\approx \sqrt{T}$ , so  $\mathbb{E}[\Pi] \rightarrow 0$ . Statement (iii) follows from the next-order expansion.

**Corollary 7.2** (Efficiency Loss). *Define the efficiency ratio  $\rho(\mu) = \mathbb{E}[\Pi](\mu)/\Pi_{\text{Kyle}}$ , where  $\Pi_{\text{Kyle}} = \sigma_z \sqrt{\Sigma_0 T}/2$ . Then  $\rho \in (0, 1)$  for all finite  $\mu$ , and  $\rho \rightarrow 1$  as  $\mu \rightarrow \infty$ .*

*Remark 7.3.* Statement (i) of Theorem 6.1 is a consistency check: when the signal arrives immediately ( $\mu \rightarrow \infty$ ), the model reduces exactly to the classical Kyle–Back (1992) model, recovering the standard profit formula.

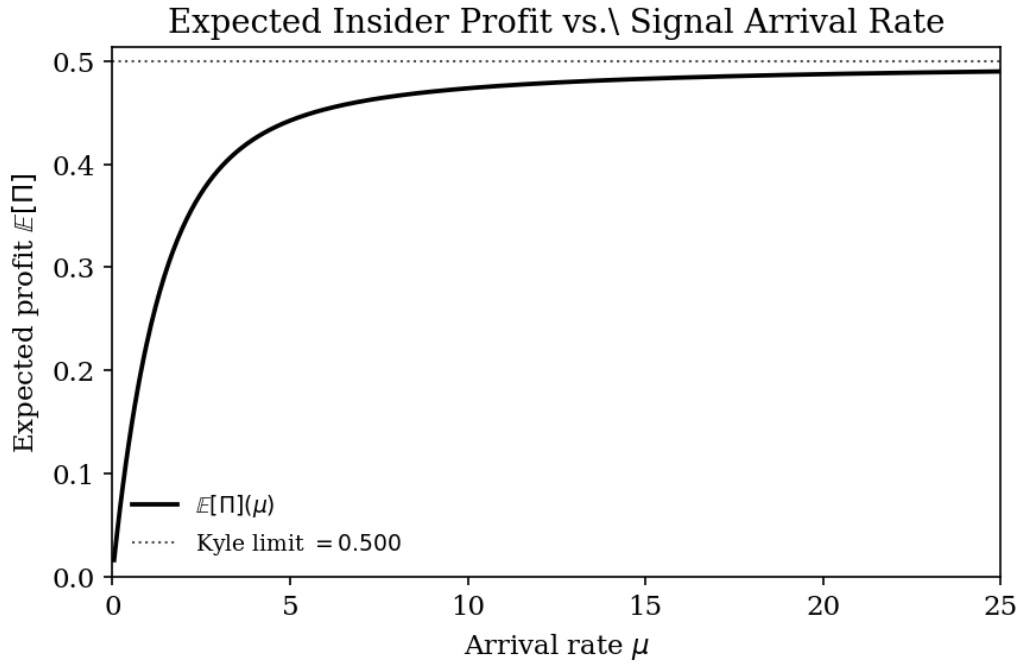


Figure 3: Expected insider profit  $\mathbb{E}[\Pi](\mu)$  as a function of the arrival rate  $\mu$ . The dotted horizontal line marks the Kyle limit  $\sigma_z \sqrt{\Sigma_0 T} / 2 = 0.5$ . The curve is strictly increasing and concave, converging to the Kyle limit from below.

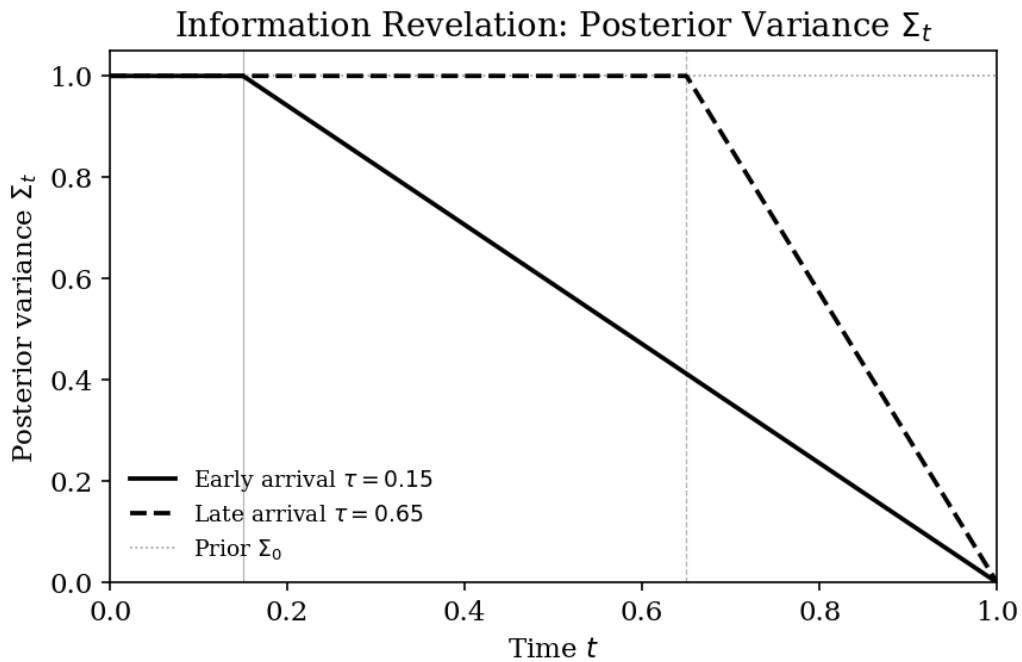


Figure 4: Posterior variance  $\Sigma_t$  for early arrival  $\tau = 0.15$  (solid) and late arrival  $\tau = 0.65$  (dashed). Before  $\tau$ ,  $\Sigma_t = \Sigma_0$  (no information); after  $\tau$ ,  $\Sigma_t$  declines linearly to zero at  $T$ , reflecting the Brownian bridge structure of the price.



## 8. Algorithm

The following pseudocode computes  $\mathbb{E}[\Pi](\mu)$  and the pre-signal value function  $V_t^{\text{pre}}$  for given parameters.

```

1 Algorithm: Random-Arrival Kyle Profit
2
3 Input: mu > 0, T > 0, Sigma_0 > 0, sigma_z > 0, time grid {t_1, ..., t_N} in
      [0, T)
4
5 Step 1. Compute Kyle baseline:
6     Pi_Kyle = (sigma_z * sqrt(Sigma_0 * T)) / 2
7
8 Step 2. Compute expected profit E[Pi](mu):
9     x <- sqrt(mu * T)
10    ef <- erfi(x) [use scipy.special.erfi or series]
11    correction <- (sqrt(pi)/(2*sqrt(mu))) * exp(-mu*T) * ef
12    E_Pi <- (sigma_z * sqrt(Sigma_0) / 2) * (sqrt(T) - correction)
13
14 Step 3. For each t_k in the time grid:
15     h_k <- T - t_k
16     x_k <- sqrt(mu * h_k)
17     ef_k <- erfi(x_k)
18     corr_k <- (sqrt(pi)/(2*sqrt(mu))) * exp(-mu*h_k) * ef_k
19     V_k <- (sigma_z * sqrt(Sigma_0) / 2) * (sqrt(h_k) - corr_k)
20
21 Step 4. For each realization tau = s in [0, T):
22     lambda_s <- sqrt(Sigma_0) / (2 * sigma_z * sqrt(T - s))
23     beta(t) <- sigma_z * sqrt(T - s) / (sqrt(Sigma_0) * (T - t)) for t in
      [s, T]
24     Pi_s <- sigma_z * sqrt(Sigma_0 * (T - s)) / 2
25
26 Output: E_Pi, array {V_k}, equilibrium coefficients {lambda_s, beta(t)}

```



## 9. References

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